

# How to access XRK files data without AiM software

Aug, 2nd 2018

We've had requests in the recent past to open xrz/xrk files in order to access the data recorded by our devices using external software. It works (beta version) also with drk files; most of the requests received till now were for MatLab( $^{\text{IM}}$ ) or custom developed software.

We developed a DLL (32 and 64 bit) that lets users accomplish this task in a very easy way. You can download two complete examples to understand how to use the DLL.

### Downloadable examples:

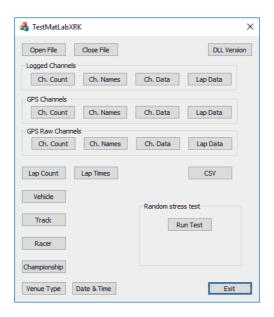
- 1. Visual Studio 2017
- 2. MatLab (™)
- 3. ...please don't forget to let us know about how you use the DLL! (write to software@aim-sportline.com)

#### **Visual Studio 2017**

Download a zipped file with full source code here:

http://www.aim-sportline.com/aim-software-betas/DLL/TestMatLabXRK 20180801.zip

Unzip the file content on your hard disk, then identify the "**TestMatLabXRK.sIn**" file and open it with Visual Studio 2010. Compile it and run it, you should see what in the following window:



It's a simple dialog window that lets you test all DLL functions.

 $All functions are documented directly in the {\it ``MatLabXRK.h''} file supplied. Few quick hints are given in the following lines.$ 

"DLL Version" has to be used to verify the DLL build time and date.

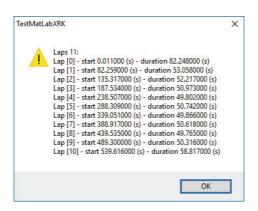




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"Lap Times" are, as well as all other timing information, given in seconds.



"Vehicle", "Racer", "Championship" and "Venue Type" refer to data set by users into AiM loggers before the on track session, "Track" is automatically identified by the AiM loggers among all the tracks previously sent to them using RS3, "Date & Time" refers to start acquisition and is managed by the loggers themselves.

Channels data values are available on a session timing base, or a lap timing base.

Logged channels are 'according to device configuration'.

GPS channels are computed by the DLL upon GPS raw channels: GPS\_Speed", "GPS\_Nsat", GPS\_LatAcc", GPS\_LonAcc", GPS\_Slope", GPS\_Heading", GPS\_Gyro", GPS\_Altitude", GPS\_PosAccuracy", GPS\_SpdAccuracy", GPS\_FreqAccuracy", GPS\_East", GPS\_North".





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### MatLab (™)

Download a zipped file with full source code here:

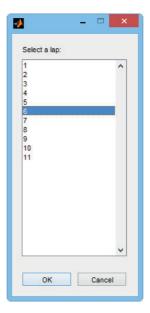
http://www.aim-sportline.com/aim-software-betas/DLL/TestMatLabXRK m 20180801.zip

This example has been developed by:
Michael Metzner, metzner software engineering
<a href="http://www.metzner-se.com">http://www.metzner-se.com</a>

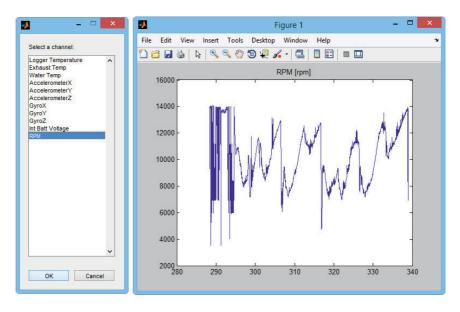
 $Unzip the file content on your hard disk, then \ load/run the "{\it XrkAccessExample.m}" file to see an example of how the dll works.$ 

When calling the example script without any filename you'll be asked to select a XRK/XRZ file. Two sample files are supplied.

After loading the file you'll have to select a lap, like in the following window:

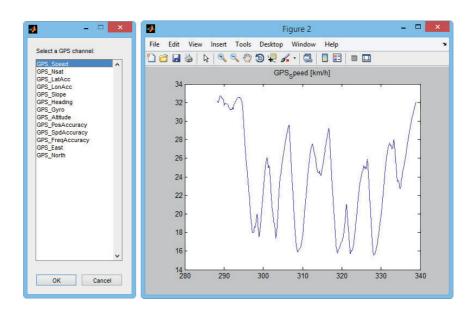


After lap selection you'll have to select a data channel and the corresponding data are plotted, like in the following two windows:

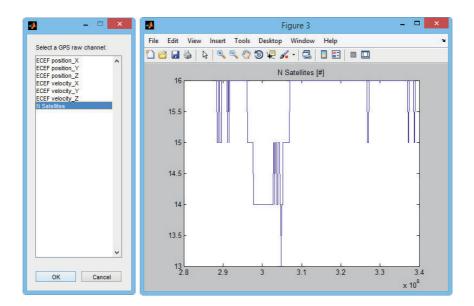




Afterwards you'll be asked to select a GPS channel and the corresponding data are plotted, see the two following windows:



 $Finally you'll\,be\,prompted\,to\,select\,a\,GPS\,raw\,data\,channel\,and\,the\,corresponding\,data\,are\,plotted.$ 





The Matlab command windows, after running the example script, will look like the following figure.

```
0
Command Window
  >> XrkAccessExample
  Feb 17 2017
  17:20:26
  track name:
                 Adria Kart
                 A.GIARDELLI
  racer name:
  championship:
  venue type:
                 2016-01-23 12:09:04
  iLapCount =
  iChannelCount =
      11
  aLapTimes =
      0.0110 82.2480
     82 2590
              52.0580
    135.3170
              52.2170
    187.5340
    238.5070
    288.3090 50.7420
    339.0510 49.8660
    388.9170 50.6180
    439.5350
              49.7650
    489.3000
              50.3160
    539.6160 58.8170
  iGpsChannelCount =
      13
  iGpsRawChannelCount =
  cGpsRawChannelNames =
    Columns 1 through 6
      'ECEP position_X'
                        'ECEF position_Y' 'ECEF position_Z' 'ECEF velocity_X' 'ECEF velocity_Y' 'ECEF velocity_Z'
    Column 7
      'N Satellites'
  cGpsRawUnits =
       1
fx >>
```